# On the role of resonance absorption in flows receptive to the magnetorotational instability

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#### Sustenance of turbulence/dynamo action in protoplanetary discs

- Presence of a linear instability mechanism?
  - Degree of ionization.
  - Different non-ideal MHD terms.
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Armitage (2011).

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# Self-sustaining processes in magnetohydrodynamics (MHD)



Field decomposition:



Toroidal field:

$$\frac{\partial \overline{b}_{y}}{\partial t} = \underbrace{-\overline{b}_{x}}_{1} + \boldsymbol{e}_{y} \cdot \overline{\nabla \times (\boldsymbol{v} \times \boldsymbol{b})} + \frac{1}{Rm} \nabla^{2} \overline{b}_{y}$$

Poloidal flux:

$$\frac{\partial \chi}{\partial t} + \frac{\partial (\psi, \chi)}{\partial (z, y)} = \underbrace{(\mathbf{v}_{3D} \times \mathbf{b}_{3D}) \cdot \mathbf{e}_y}_2 + \frac{1}{Rm} \nabla^2 \chi$$

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Ω-effect

Peedback electromotive force (EMF)

(Rincon et al. 2007, Rincon et al. 2008)

# Alfvén resonance & resonant absorption

Research question:

What is the shape and the location of the electromotive force (EMF)?

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Consider a system with a continuous background flow V(x), a magnetic field B(x), and a wave with wavenumber vector k giving the flow frequency  $\omega_f = V \cdot k$  and Alfvén frequency  $\omega_A = B \cdot k$ :

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- At these resonance points, energy is absorbed due to phase mixing.
- This absorption process is independent on resisitivity and viscosity.
- As a consequence of the absorption, resonance layers may act as barriers that delimit fluid/plasma motion.

(Barston, 1964; Booker & Bretherton, 1967; Grad, 1969; Uberoi, 1972)

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• Consider the linearized incompressible ideal Euler and induction equation in cylindrical coordinates

$$\partial_t \mathbf{v} + (\mathbf{V} \cdot \nabla)\mathbf{v} + (\mathbf{v} \cdot \nabla)\mathbf{V} - (\mathbf{B} \cdot \nabla)\mathbf{b} - (\mathbf{b} \cdot \nabla)\mathbf{B} = -\nabla\pi$$
$$\partial_t \mathbf{b} + (\mathbf{V} \cdot \nabla)\mathbf{b} + (\mathbf{v} \cdot \nabla)\mathbf{B} - (\mathbf{B} \cdot \nabla)\mathbf{v} - (\mathbf{b} \cdot \nabla)\mathbf{V} = 0$$
$$\nabla \cdot \mathbf{v} = 0, \quad \nabla \cdot \mathbf{b} = 0,$$

with a basic state:

$$V(r) = [0, V_{\theta}(r), V_{z}(r)], \quad B(r) = [0, B_{\theta}(r), B_{z}(r)],$$

and a perturbation  $[\mathbf{v}, \mathbf{b}, \pi](r, \theta, z, t) = [\hat{\mathbf{v}}, \hat{\mathbf{b}}, \hat{\pi}](r)e^{i(m\theta + kz - \omega t)}$ .



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• By solving the induction equation for  $\hat{b}$  and expressing  $\hat{v}$  in terms of a Lagrangian displacement  $\xi$ , one obtains the equation system

$$\begin{bmatrix} \begin{pmatrix} C_1 - \frac{D}{r} \end{pmatrix} & -C_2 \\ C_3 & -C_1 \end{bmatrix} \begin{pmatrix} \xi_r \\ \pi \end{pmatrix} = D \begin{pmatrix} \xi'_r \\ \pi' \end{pmatrix},$$

where  $C_1$ ,  $C_2$  and  $C_3$  are coefficients that depend on m, k, r, B, V and

$$\omega_f = \frac{V_{\theta}}{r}m + V_z k, \quad \Omega = \omega - \omega_f, \quad \omega_A = \frac{B_{\theta}}{r}m + B_z k, \quad D = \Omega^2 - \omega_A^2.$$

(Goossens et al. 1992)

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• The system has a singularity at  $r = r_A$  where D = 0. Let  $s = r - r_A \ll 1$  and assume that  $\xi_r$  and  $\pi$  may be described by modified power series solutions in s:

$$\xi_r(s) = \sum_{n=0}^{\infty} X_n s^{\sigma+n}, \qquad \pi(s) = \sum_{n=0}^{\infty} Y_n s^{\sigma+n}$$

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- Introduce a small growth rate  $\alpha \sim O(s)$  that shifts the singularity away from the real axis:  $\omega \to \omega + i\alpha$ ,  $r_A \to r_A + i\chi(\alpha)$ .

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- Taylor expand all functions of  $\omega$  in  $\alpha \ll 1$ .

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# Electromotive force (EMF)





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# Electromotive force (EMF)

- Describes the induction of the magnetic field.
- Perturbation electromotive force (EMF),

$$\begin{aligned} \mathcal{E} &= \left( \hat{\mathbf{v}} e^{i(m\theta + kz - [\omega + i\alpha]t)} + \hat{\mathbf{v}}^* e^{-i(m\theta + kz - [\omega + i\alpha]t)} \right) \\ &\times \left( \hat{\mathbf{b}} e^{i(m\theta + kz - [\omega + i\alpha]t)} + \hat{\mathbf{b}}^* e^{-i(m\theta + kz - [\omega + i\alpha]t)} \right) \end{aligned}$$

• Study the steady mean component of the forcing.



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$$\begin{aligned} \mathbf{r} : & A e^{\pm \phi \sigma_{i}} \left\{ \frac{2kT}{D^{(1)}(m^{2} + k^{2}r_{A}^{2})} \frac{1}{s^{2} + \chi^{2}} \times \right. \\ & \left[ sr_{A} \left( \Omega \omega_{A}^{\prime} - \Omega^{\prime} \omega_{A} \right) \mp \chi \left( kr_{A}^{2} \left( \omega_{f} \left( \frac{V_{\theta}}{r} \right)^{\prime} + \Omega \left( \frac{B_{\theta}}{r} \right)^{\prime} \right) - m \left( \omega_{f} V_{z}^{\prime} + \Omega B_{z}^{\prime} \right) \right) \pm \alpha \omega_{f} \frac{4kT}{D^{(1)}} - \alpha \chi r_{A} \omega_{f}^{\prime} \mp \alpha s \left( \left( \frac{B_{\theta}}{r} \right)^{\prime} kr_{A}^{2} - B_{z}^{\prime} m \right) \right] + r_{A} \left( B_{z}^{\prime} \left( \frac{V_{\theta}}{r} \right)^{\prime} - V_{z}^{\prime} \left( \frac{B_{\theta}}{r} \right)^{\prime} \right) \right\}, \\ \theta : & 4A\alpha \frac{kT \omega_{f}}{D^{(1)}(m^{2} + k^{2}r_{A}^{2})} e^{\pm \phi \sigma_{i}} \frac{kr_{A} s \mp m\chi}{s^{2} + \chi^{2}}, \qquad z : & 4A\alpha \frac{kT \omega_{f}}{D^{(1)}(m^{2} + k^{2}r_{A}^{2})} e^{\pm \phi \sigma_{i}} \frac{ms \pm kr_{A}\chi}{s^{2} + \chi^{2}}, \end{aligned}$$

# Validation of the EMF expression

Numerical ideal MHD calculations (Ogilvie & Pringle, 1996):

Background state:  $V(r) = [0, r\Omega_K(r), 0]$ ,  $B(r) = [0, B_0r^{-1}, 0]$ , with  $B_0 = 0.2$  and  $\Omega_K(r) = r^{-3/2}$  is the Keplerian profile.



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No-slip, electr. conducting walls;  $Re = 10^3$ , Pm = 1, R = -4/3;  $B = (0, B_0, 0)$ 



Rotating plane Couette flow



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$$k = 4, m = 2,$$
  
 $\omega = 1.49 - i0.00$ 

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- Future work: Analytical expression for the EMF in an axially modulated flow. Ansatz: [v, b, π](x, y, z, t) = [v, b, π](x, z)e<sup>i(my-ωt)</sup>

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Thank you for your attention!

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